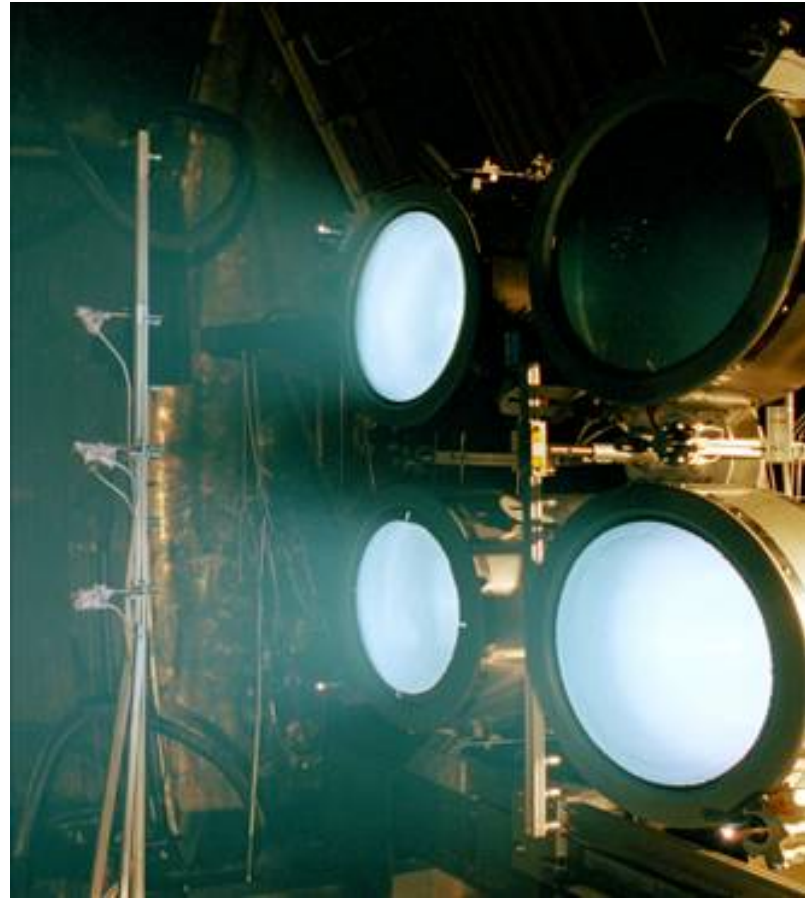


# NASA's Evolutionary Xenon Thruster

The NEXT Ion Propulsion  
System for Solar System  
Exploration

Briefing prepared for New  
Frontiers AO  
June 2008

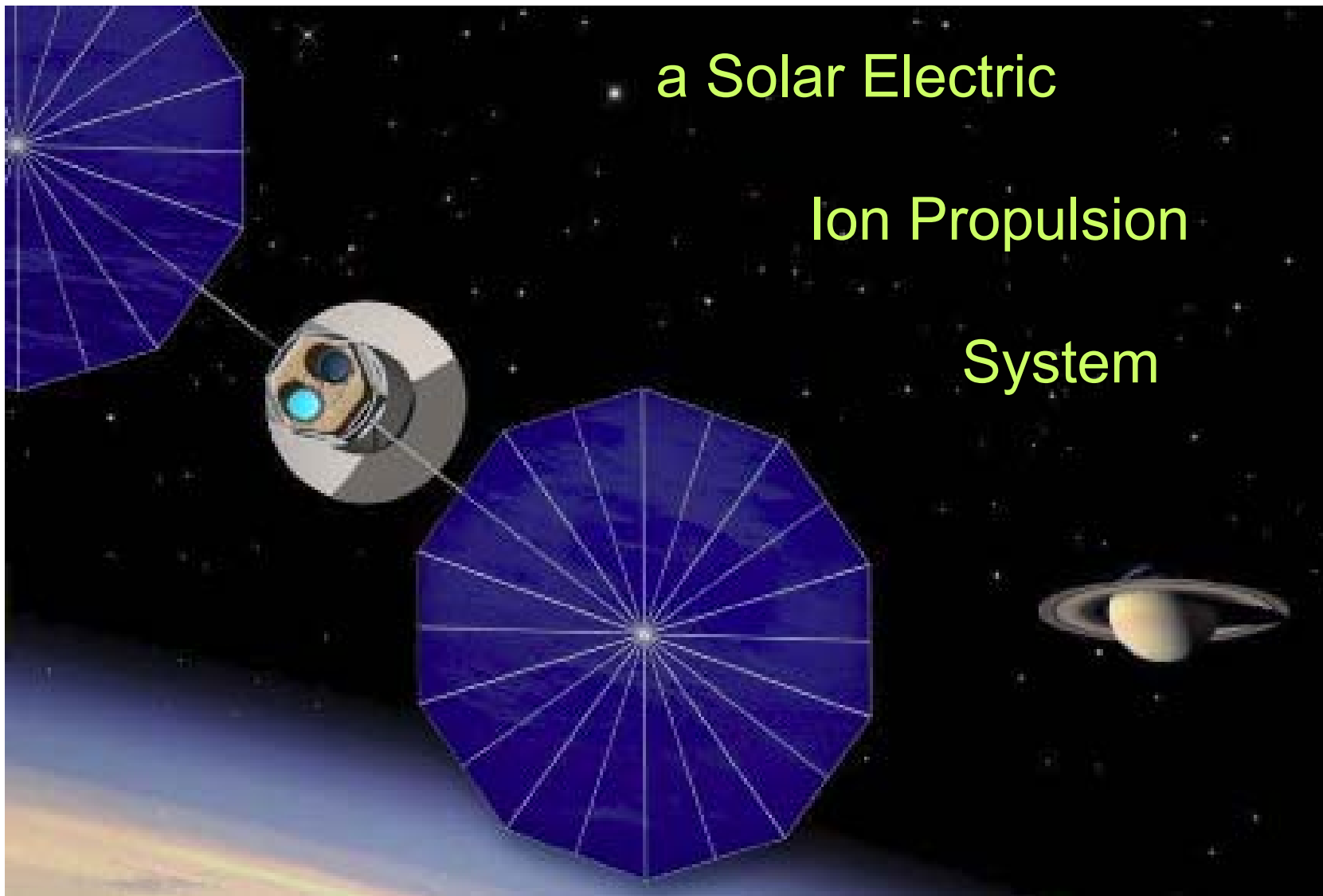


# NEXT is:

## a Solar Electric

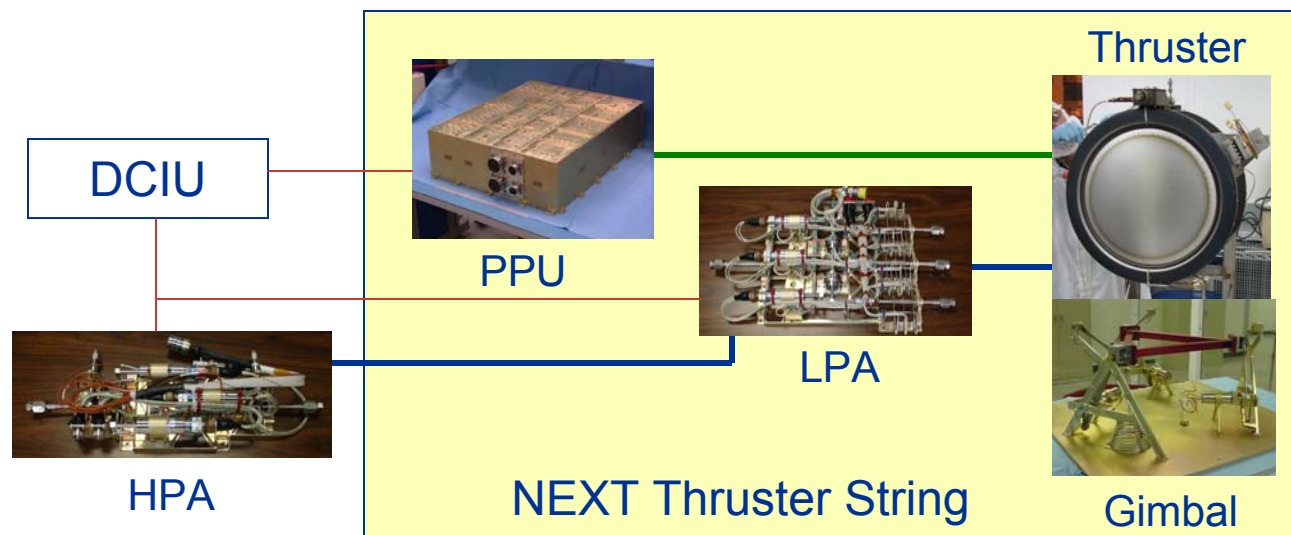
## Ion Propulsion

## System



# The NEXT System

- Thruster String composed of Thruster/Gimbal Assembly, Power Processing Unit (PPU), and Propellant Management System (PMS) Low Pressure Assembly (LPA)
- High Pressure Assembly (HPA) and DCIU complete system
- Thruster Strings are added for mission performance reasons and for failure tolerance (Nomenclature: N+1)
- Overall system is configurable to meet mission needs





# The State of NEXT

- The NEXT project is advancing the capability of ion propulsion to meet NASA robotic science mission needs
- Mission analyses have demonstrated beneficial NEXT application over a range of missions from Discovery to Flagship
- Key ion propulsion system hardware has advanced to a high state of maturity
  - Testing to date is very successful
- The project is striving to ease transition to flight by addressing Dawn lessons learned and user needs
- First-user implementation and cost modeling will help users to assess NEXT, and to focus project resources on higher pay-off activities



# NEXT Project Background

- Two-phase project to develop Next Generation Ion (NGI) technology to Technology Readiness Level (TRL) 5/6
  - Sponsored by NASA Science Mission Directorate, conducted under MSFC In-Space Propulsion Technology Program
  - Implemented through a NRA
  - First Phase: 1 year, completed August, 2003
  - Second Phase: Initiated October, 2003



## The NEXT Team & Contacts

- **NASA Glenn Research Center** - Technology Project Lead
  - Michael Patterson, Principal Investigator, 216-977-7481
  - Scott Benson, Project Manager, 216-977-7085
  - George Soulas, GRC Thruster Lead, 216-977-7419
- **Jet Propulsion Laboratory** - System Integration Lead
  - Steve Snyder, System Integration Lead, 818-393-7357
- **Aerojet**, Redmond WA - Thruster, PMS, DCIU Simulator
  - Nicole Meckel, Aerojet Project Lead, 425-936-6569
  - Andy Hoskins, Aerojet Project and Thruster Lead, 425-936-6562
  - Randy Aadland, Propellant Management System Lead, 425-936-5251
  - Jeff Monheiser, DCIU Simulator Lead, 425-936-6663
- **L3 Comm ETI**, Torrance CA - PPU
  - Brian Wong, L3 Project Lead, 310-517-6099
  - Phil Todd, PPU Lead, 310-517-6859
- Participation by **APL, Univ. of Michigan, Colorado State Univ.**
  - Carl Engelbrecht, APL



# NEXT Capabilities, Benefits and Applications



## NEXT significantly improves performance over State-of-Art (SOA) EP

CHARACTERISTIC	NSTAR (SOA)	NEXT	BENEFIT
Max. Thruster Power (kW)	2.3	6.9	Enables high power missions with fewer thruster strings
Max. Thrust (mN)	91	236	
Throttling Range (Max./Min. Thrust)	4.9	13.8	Allows use over broader range of distances from Sun
Max. Specific Impulse (sec)	3120	4190	Reduces propellant mass, thus enabling more payload and/or lighter spacecraft
Total Impulse ( $10^6$ N-sec)	4.6	>18	Enables low power, high $\Delta V$ Discovery-class missions with a single thruster
Propellant Throughput (kg)	150	450	





# Mission Benefits

- Numerous mission analyses performed during NEXT project have demonstrated mission benefits

Mission	Performance Finding
<b>Discovery - Small Body Missions</b> <ul style="list-style-type: none"> <li>Near Earth Asteroid Rendezvous</li> <li>Vesta-Ceres Rendezvous (Dawn-like)</li> <li>Comet Rendezvous</li> <li>Deimos Sample Return</li> </ul>	Higher net payload mass with fewer thrusters than NSTAR system
<b>New Frontiers -</b> <ul style="list-style-type: none"> <li>Comet Surface Sample Return</li> </ul>	Higher net payload mass than NSTAR, with, Simpler EP System: 2+1 NEXT vs 4+1 NSTAR thrusters
<b>New Frontiers -</b> <ul style="list-style-type: none"> <li>Titan Direct Lander</li> </ul>	> 700 kg entry package with 1+1 NEXT system
<b>Flagship - Saturn System Missions</b> <ul style="list-style-type: none"> <li>Titan</li> <li>Enceladus</li> </ul>	> 2400 kg to Saturn Orbit Insertion with 1+1 NEXT system, Earth Gravity Assist and Atlas 5 EELV - Doubles delivered mass of chemical/JGA approach > 4000 kg to Saturn Orbit Insertion with 3+1 NEXT system, Earth Gravity Assist and Delta IV Heavy



# NEXT - System & Integration Benefits

- NEXT retains critical heritage to NSTAR, while addressing complex system integration issues encountered on Dawn
- NEXT thruster is very similar to NSTAR thruster in physics, concept, and functions
  - High relevance in transferring NSTAR thruster life and throttling knowledge to NEXT thruster validation
- NEXT PPU encompasses functionality of NSTAR PPU
  - Additional functions simplify system and improve efficiency across throttle table
  - Main advances are in modularity and producability of unit
- Spacecraft integration is simplified by NEXT capabilities and features
  - Less thruster strings per mission total impulse
  - Modular, simplified xenon feed system
  - PPU is compatible with wider baseplate thermal range than NSTAR
  - Gimbal has smaller footprint than NSTAR



# System Requirements

- Project Requirements are documented and controlled in:
  - Project Requirements Document (In-Space Req'ts)
  - Technical Requirements & Validation Document (Flowdown)
- Requirements developed :

Source	Requirement
NSTAR Heritage	Functional, design
Deep Space Design Reference Mission	Performance, environmental
Refocus Analyses	Throttling range, 300 kg throughput

- Requirements and design reviewed:
  - System Requirements and Integration Reviews
  - Subsystem and System-Level Design Reviews
  - Independent Review
- Formal Project Documentation
  - Plans: Project, Risk Management, Validation, Assurance
  - System ICD



# NEXT Development Status

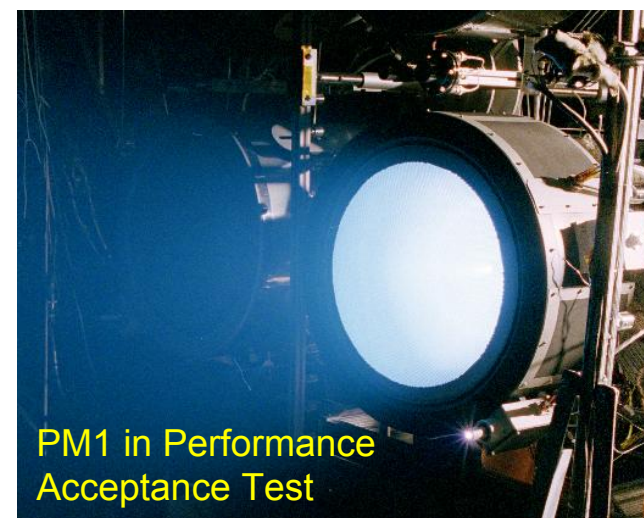
# Thruster

- The Engineering Model (EM) and Prototype Model (PM) NEXT ion thruster designs were derived from a laboratory model 40 cm beam diameter ion thruster developed in 2001 at the NASA Glenn Research Center (GRC)
- The EM thruster design was subsequently developed at GRC
- The PM thruster design was developed at Aerojet under contract to GRC, and matures the NEXT thruster design to ensure full-compliance with structural and thermal requirements, and improve thruster manufacturability



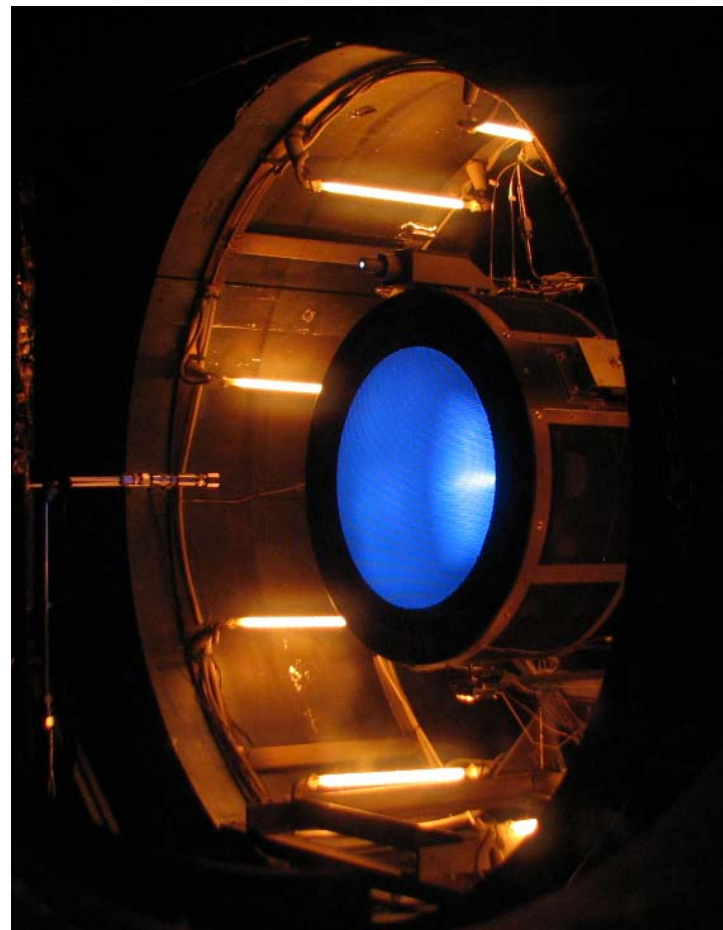
# Thruster Characteristics

- 0.54 – 6.9 kW thruster input power
- Ring-cusp electron bombardment discharge chamber
- 36 cm beam diameter, 2-grid ion optics
- Beam current at 6.9 kW: 3.52 A
- Maximum specific impulse > 4170 sec
- Maximum thrust > 236 mN
- Peak efficiency > 70%
- Xenon throughput > 300 kg, 450 kg qualification level
  - Analysis-based capability >450 kg
- Mass is 12.7 kg (13.5 kg with cable harnesses)



# NEXT Thruster

- Prototype Model Thruster (PM1) delivered by Aerojet to GRC
  - Flight-level design and fabrication processes
- Performance Acceptance Testing successfully completed at GRC
- Comprehensive PM1 environmental test sequence completed at JPL
- Two cycles of acceptance & environmental testing completed
  - Thruster reworked to resolve minor design issues
- PM1 now supporting System Integration Testing
- PM1 thruster to be incorporated into life validation program upon completion of testing

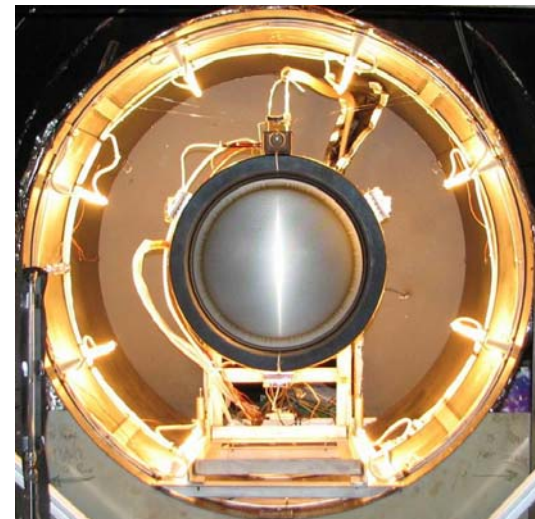


**PM Thruster undergoing Thermal Vacuum Testing at JPL**



# Thruster Environmental Testing

- Thermal balance test performed to gather key thruster thermal data over wide range of operating and environmental conditions
  - Develop and validate thruster thermal model
  - Demonstrate thruster operation and temperature margins over large temperature range
- Integrated thruster/gimbal qualification-level vibe testing
  - 10.0 Grms, 3 axes, 2 min/axis
  - No changes in pre- and post-vibe gimbal functional results
- Thruster Thermal/Vacuum test to qualification levels
  - $< -120^{\circ}\text{C}$  cold
  - $> 203^{\circ}\text{C}$  hot (at reference location)
  - 3 cycles with hot and cold dwell
  - Hot and cold thruster starts







# Development/Environmental Test Findings

- PM thruster performs within predictions and is consistent with results from multiple EM thrusters
- PM thruster has significant thermal margin on critical components
  - Harness outer layer at thruster body exit needs to be resolved
- PM thruster compatible with dynamic and thermal environments
- Thruster performance was nominal over entire test sequence
- Implementation of EM to PM design and fabrication transition was very successful
- Gimbal is compatible with dynamic environments



## PM Thruster Planning

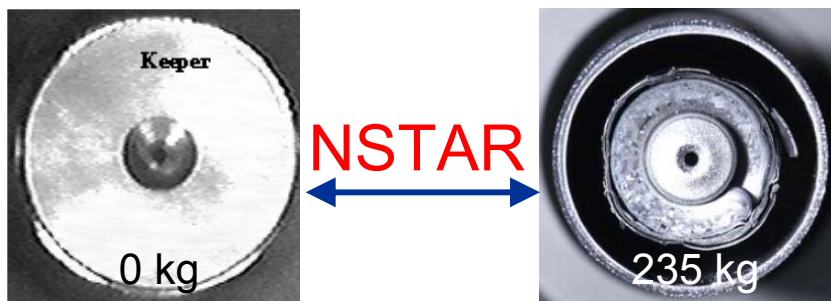
- PM1R to be incorporated into life validation program upon completion of system integration testing
  - Wear test of PM1R
- All thruster drawings and work instructions have been updated at Aerojet
  - Incorporated all redlines
  - Reflects PM1R as-built configuration
  - Released to development level
- PM2 parts and subassemblies to be put into controlled storage for later In-Space or user final assembly

# NEXT Thruster Life Validation

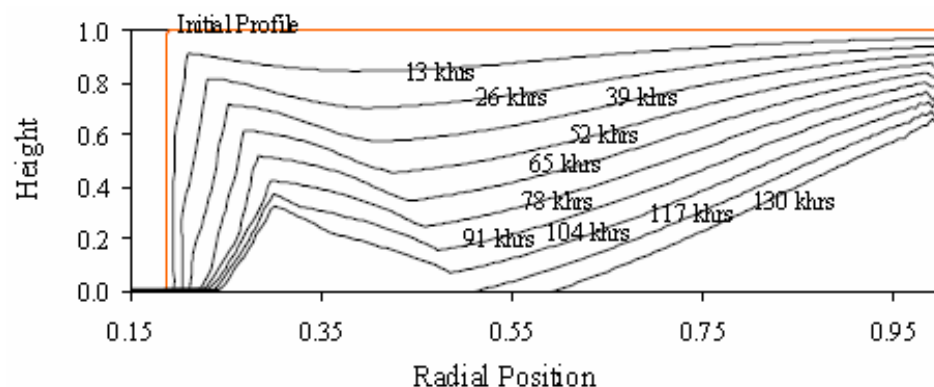
- Thruster life validation continuing through EM3 long duration testing and life analyses (*VF16, GRC Bldg 16*)
- Predicted capability exceeds 730 kg xenon throughput
- Highest mission-derived requirement  $\approx 300$  kg xenon throughput
  - Near-Earth Asteroids:  $< 200$  kg
  - Comet Rendezvous: 260 kg
  - Saturn mission: 225 - 275 kg
  - Comet Sample Return: 300 kg
- $> 16,300$  hrs,  $> 334$  kg xenon throughput demonstrated to date (as of 6/20/08)
  - $> 13.2 \times 10^6$  N-s total impulse
- Milestones
  - Exceeded NSTAR ELT throughput: Sept. 2007
  - Exceeded 300 kg project design throughput: Mar 2008
- Continued testing and analysis will support FY08/09 competed mission proposals



# LDT and Life Validation: NEXT Thruster Discharge Keeper Erosion Rates within Expectations



**Discharge Keeper erosion mitigated in NEXT**

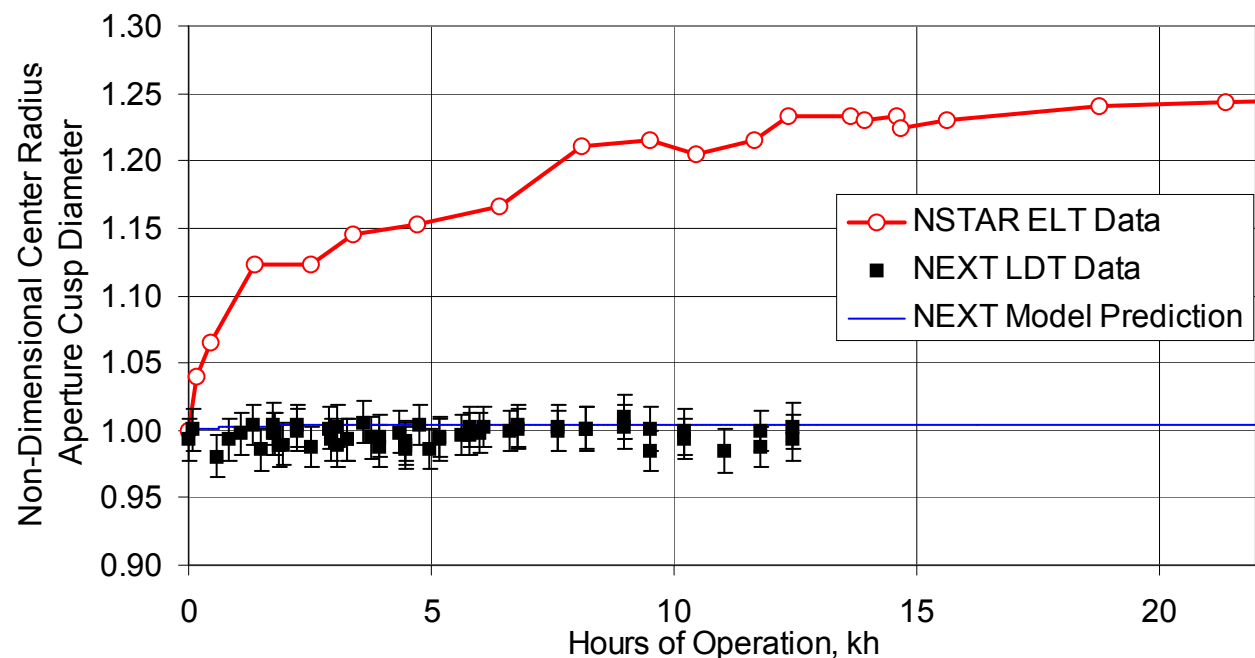


**DCA Graphite Keeper Erosion Estimates from NEXT Service Life Assessment Model**

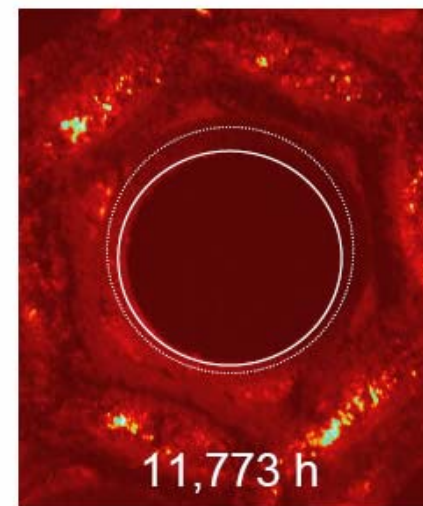
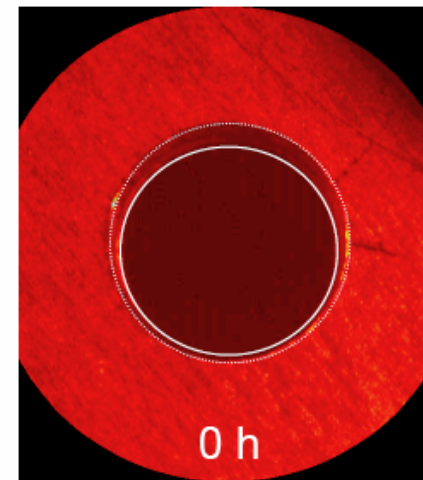
Prediction assuming continued full power operation

**NEXT Design Mitigates Critical Erosion observed in other Ion Thrusters**

# LDT and Life Validation: NEXT Thruster Aperture Erosion Rates within Expectations

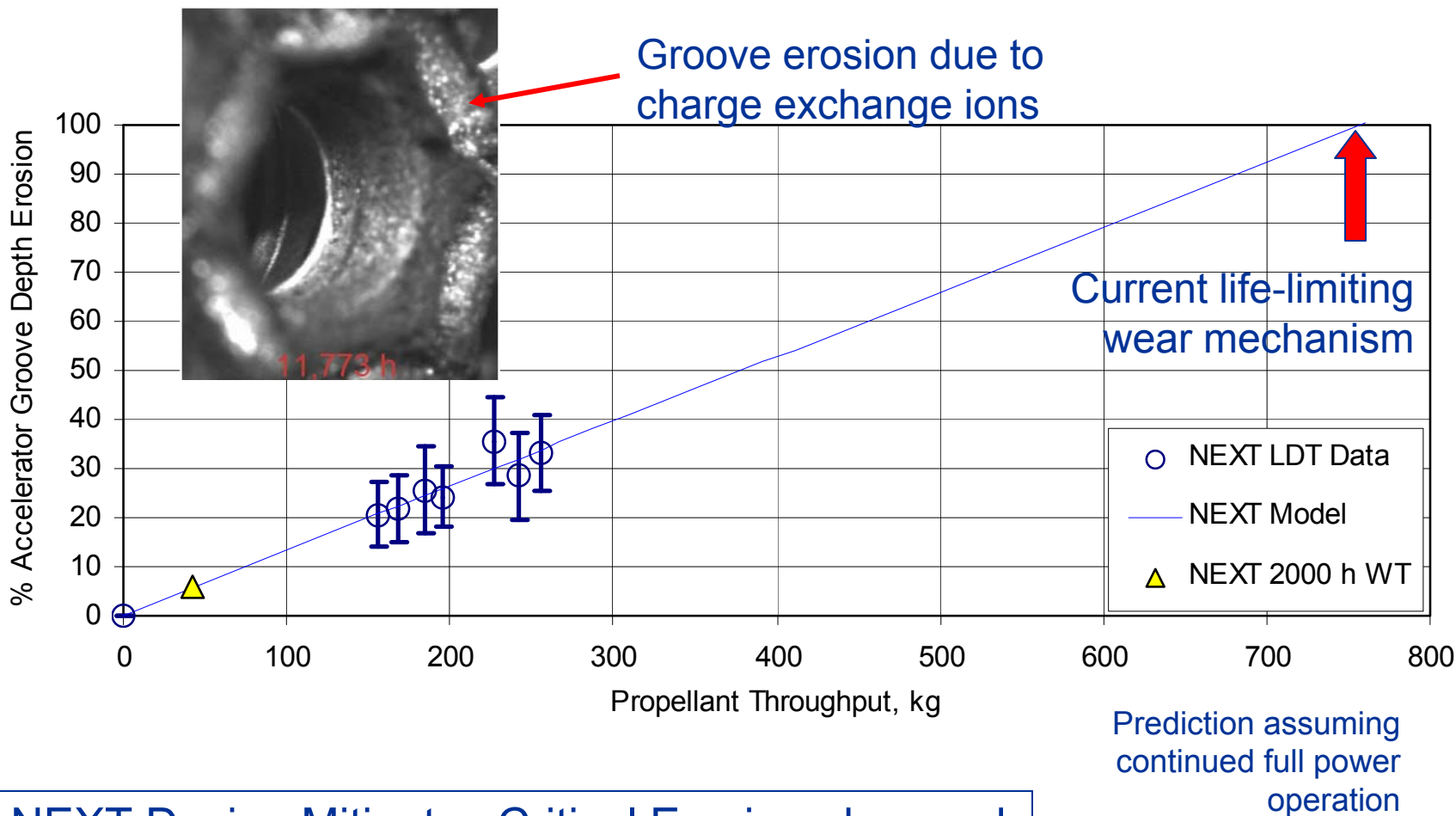


Prediction assuming  
continued full power  
operation



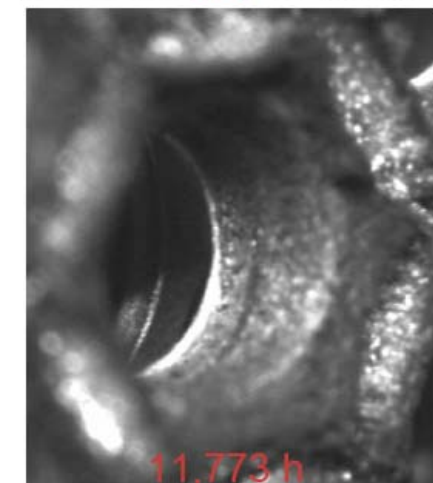
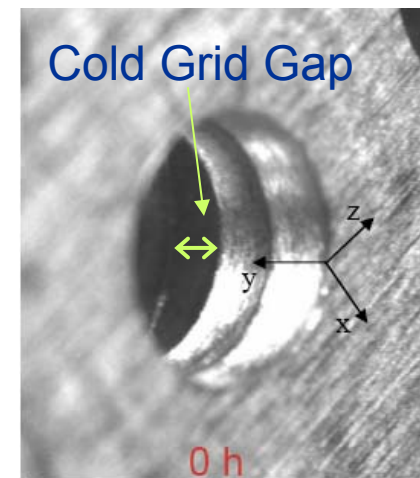
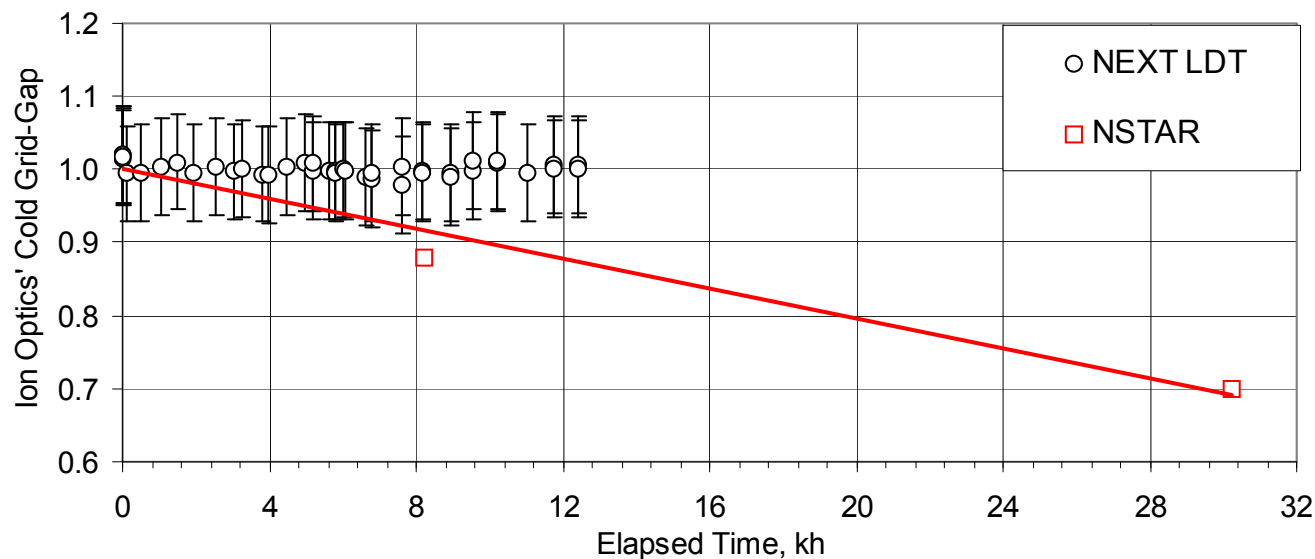
NEXT Design Mitigates Critical Erosion  
observed in other Ion Thrusters

# LDT and Life Validation: NEXT Accelerator Groove Erosion Rates within Expectations



NEXT Design Mitigates Critical Erosion observed in other Ion Thrusters

# LDT and Life Validation: NEXT Grid Gap within Expectations



NEXT Ion Optics Design Compliant and Stable





# LDT and Life Validation: Detailed Throttling Strategy Developed

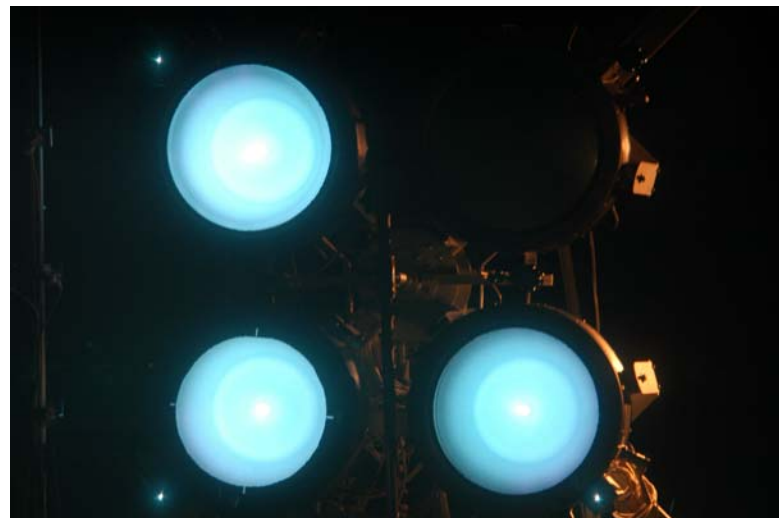
Operating Condition Bin	Recommended Duration, kh	Segment Throughput, kg	Total Post-Segment Throughput, kg	Estimated End of Segment Date
3.52A, 1800V	13.0	267.4	267.4	11/17/2007
3.52A, 1179V	4.0	82.3	349.7	6/12/2008
1.20A, 1021V	2.0	14.6	364.3	9/12/2008
3.52A, 1800V	3.0	61.7	426.0	2/16/2009
1.00A, 275V	3.0	19.9	445.9	7/5/2009
1.20A, 1800V	2.0	14.6	460.5	10/5/2009
Totals	27.0	460.5		

- Achieves the following:
  - Demonstration of >450 kg throughput per PRD and TRV by end of FY09
  - Total LDT duration > average mission thruster operating time
  - Demonstrate total impulse greater than mission requirement ( $1.75 \times 10^7$  N-sec)
  - Demonstrate intermediate power operation consistent with mission analyses
  - Demonstrate power throttling back to full-power consistent with mission analyses
  - Demonstrate low-power operation (< 0.5 kW) for 2X the average mission analyses duration
  - Operates at known worst-case wear conditions



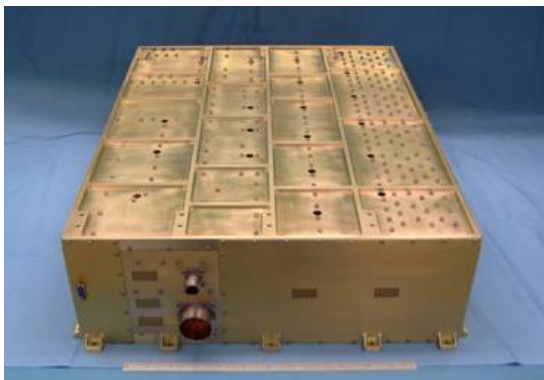
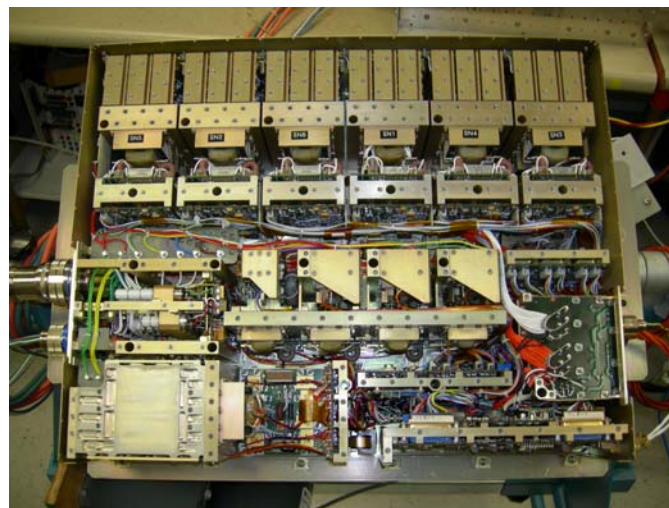
# NEXT Multi-Thruster Array Test

- Objectives
  - Assess thruster and plasma interactions, with sensitivities to thruster spacing, gimbaled thrusters, and neutralizer operating modes
- Configuration
  - Four GRC EM thrusters, three operating and one instrumented non-operating
  - Extensive diagnostics to collect data for multi-thruster system modeling and analyses
- Completed in December 2005 at GRC
- Single, Dual and Triple thruster operations conducted
- Initial data indicates expected performance was achieved, well-understood operations, without significant sensitivity to system configuration



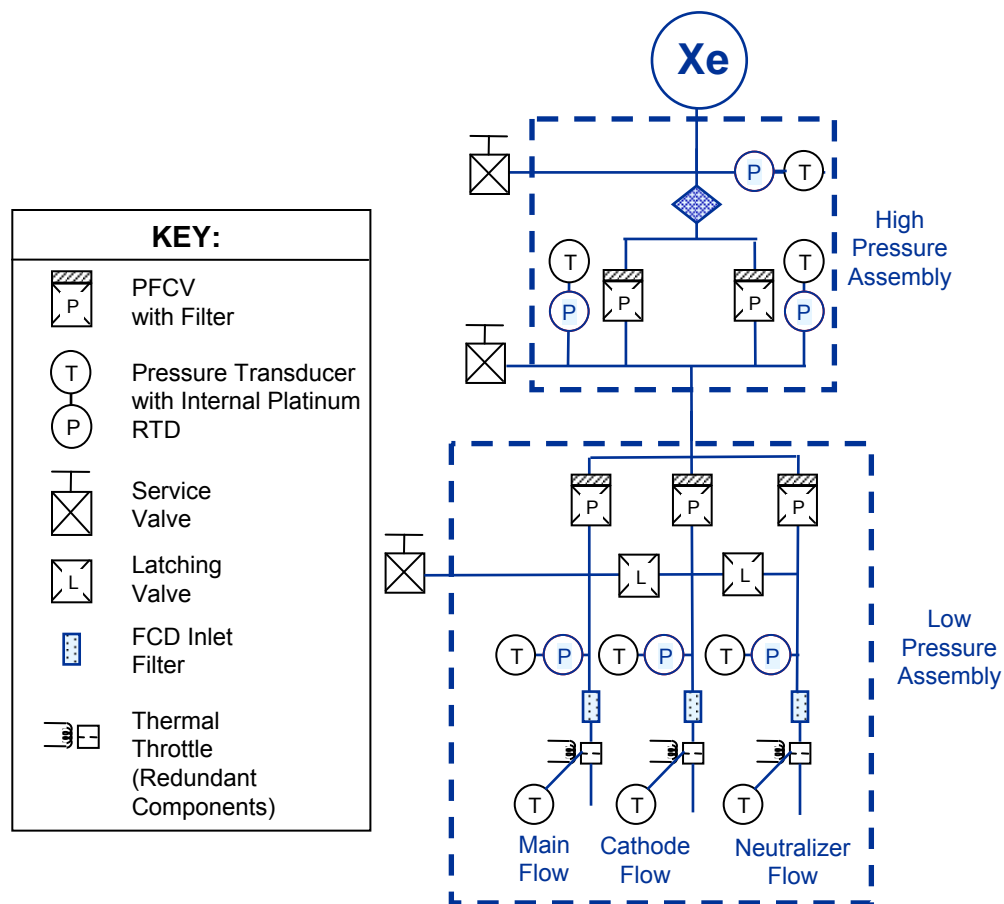
# Power Processing Unit

- EM PPU fabrication completed
- Integration testing on-going at GRC
- Thorough unit testing to follow
  - Qual-level vibration testing and post-vibe functional
  - Qual-level thermal/vacuum test
  - EMI/EMC tests
- Testing planned to be complete in CY2008
- DCIU to be integrated in next development phase

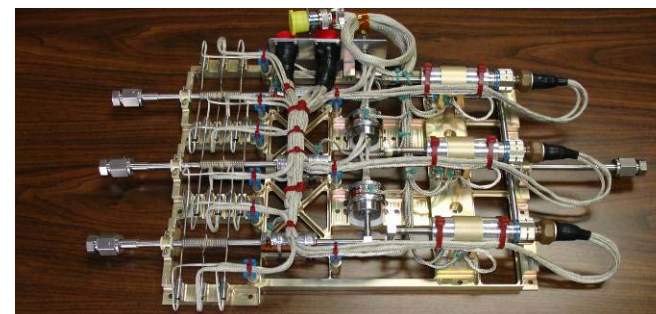


- Flexible, scalable architecture can be adapted to a wide range of thrusters and missions
- Wide throttle range capability: 250W to 7200W
- > 0.2 kW/kg Specific Power
- Simple thermal interface - 65 C baseplate

# Propellant Management System (PMS)



**NEXT PMS**  
High Pressure Assembly  
(Aerojet)



**NEXT PMS**  
Low Pressure Assembly  
(Aerojet)

NEXT PMS provides significant volume and mass reduction over DS-1/Dawn approach



# Propellant Management System

- All EM PMS assemblies are complete
  - 2 HPA's, one Flight-like
  - 3 LPA's, one Flight-like
  - Non-flight assemblies are identical except for use of lower cost equivalent parts
- All assemblies have completed functional tests
- Flight-like LPA and HPA successfully completed qual-level vibration testing and post-vibe functional testing
  - 14.1 Grms for 2 minutes in each axis
- Qual-level thermal/vacuum testing successfully completed
  - +12 to +70 °C temperature range, 3 cycles
- EM PMS has been delivered to NASA for use in system integration testing

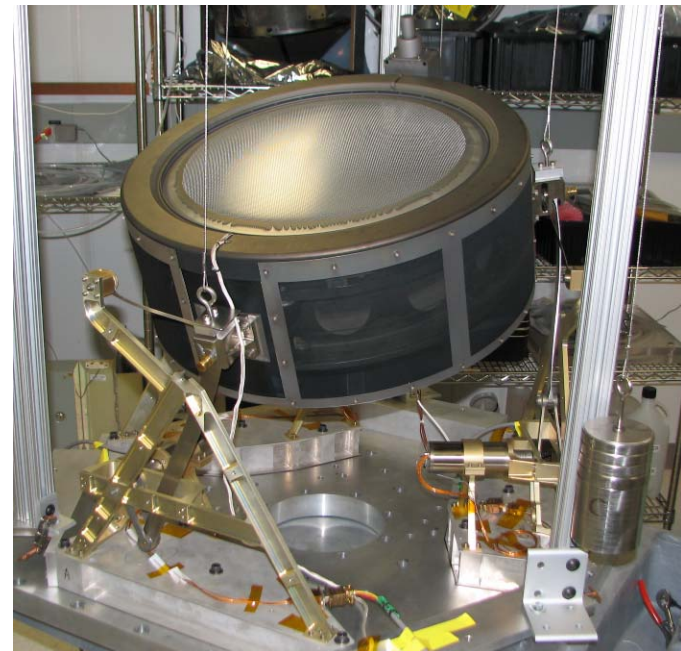


# Digital Control Interface Unit

- DCIU Simulators have been completed and are in use in tests
- Laptop-based test equipment, with EM-level PMS pressure loop control cards
- Capable of operating 3 thruster string system
- Validates control algorithms and PMS control card
- Supports
  - PPU input/output testing
  - PMS control during testing
  - Single-String and Multi-String Integration Tests
  - PMS kernel control in Long Duration Test

# Gimbal

- Breadboard gimbal
  - Designed and fabricated by Swales Aerospace
  - Flight-like design using JPL-approved materials with certifications
    - Stepper motors have space-rated option
  - Mass < 6 kg
  - Two-axis range of motion:  $\pm 19^\circ$ ,  $\pm 17^\circ$
- Successful functional testing with PM1 engine
- Gimbal passed two qual-level vibration tests and low-level shock tests with minor issues
- Good baseline – few if any modifications needed to move into qual program
  - Need to perform torque margin tests with harness and propellant line routing

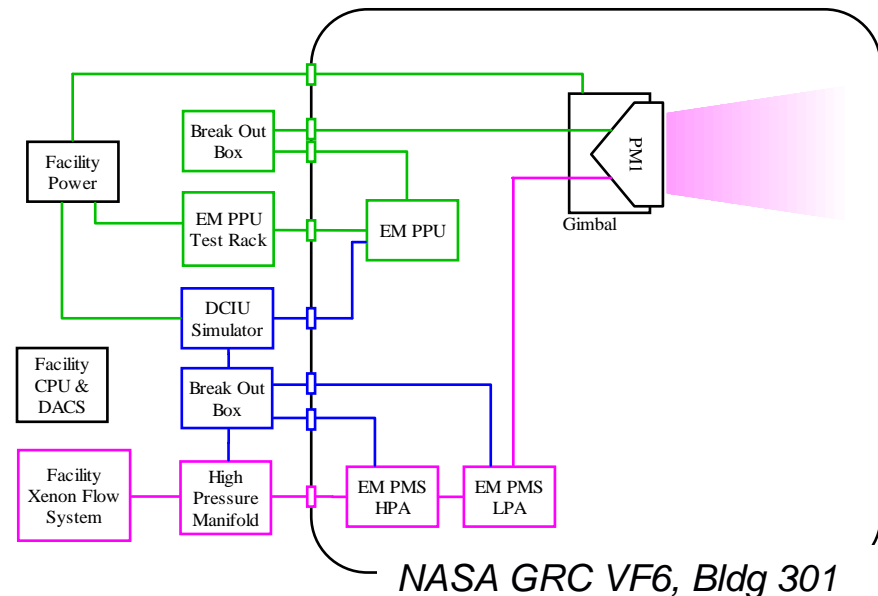






# Single String and Multi-Thruster System Integration Testing

- Scope
  - Verify that the integrated system of NEXT components meets the project requirements
  - Verify the interfaces between the system components
- Primary Objectives
  - Demonstrate operation of thruster over throttle table with PPU and PMS
  - Demonstrate operation of system at off-nominal conditions
  - Demonstrate recycle and fault protection operation
- Status
  - System Integration Testing was initiated in May 2008.
  - Test will continue through July 2008.








- 104 separate requirements have been flagged for validation
  - Component functionals
  - Performance requirements
  - Environmental requirements
  - Interface requirements
  - Power allocations



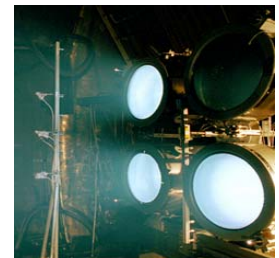
# NEXT is Nearing TRL6 Validation

- Critical tests have been completed, or are imminent, on high fidelity hardware

	PM1 	PM1R 	PPU 	Feed System 	Gimbal 
Functional & Performance Testing	Complete	Complete	Complete*	Complete	Complete
Qual-Level Vibration Test	Complete*	Complete	FY08	Complete	Complete
Qual-Level Thermal/ Vacuum Test	Complete	Complete	FY08	Complete	N/A

\* - Test findings addressed in unit rework

- Single-String and Multi-String System Integration Testing CY2008
- Thruster Life Test: In progress & continuing through FY2010



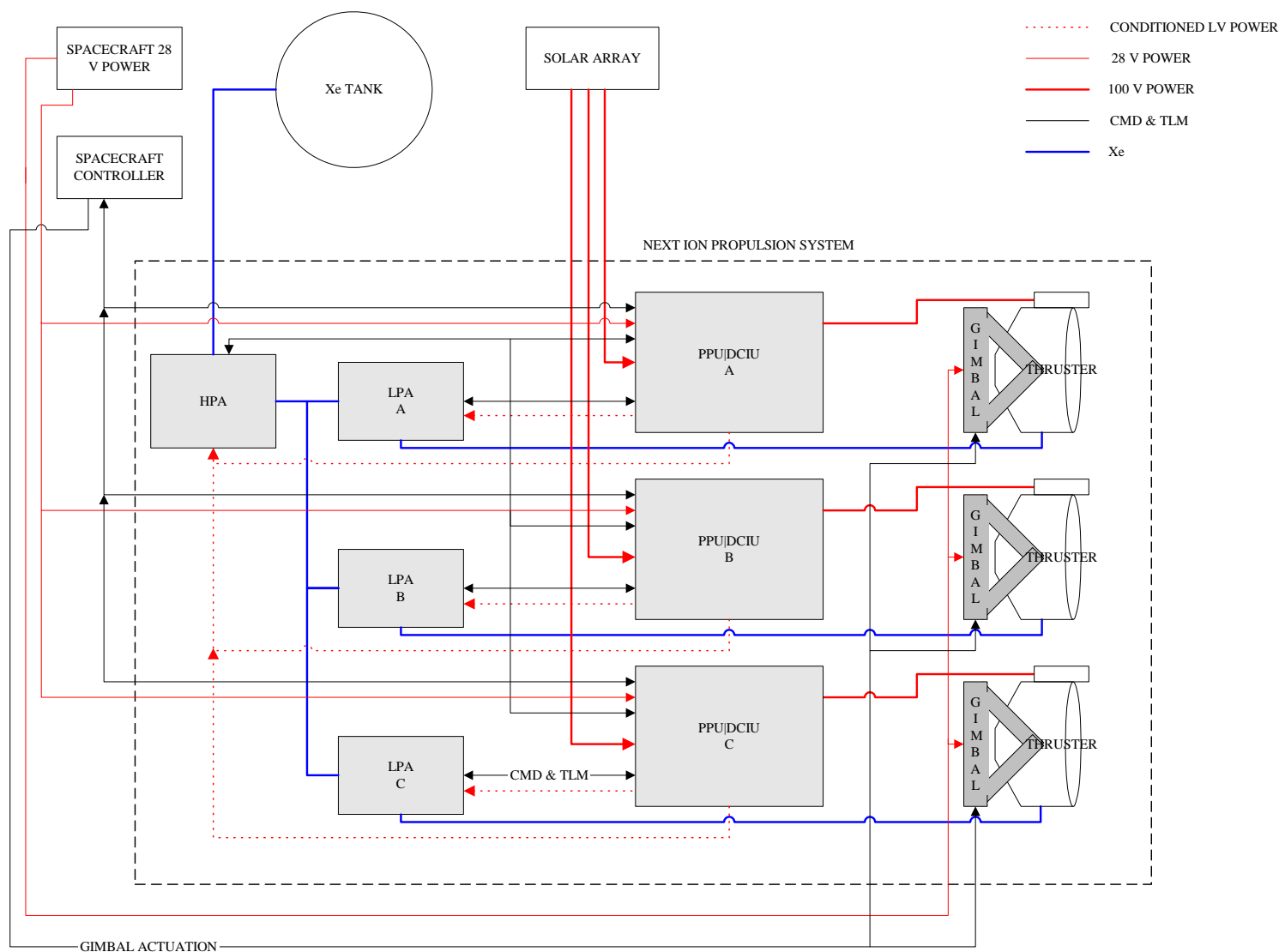




# NEXT System



# NEXT IPS 3-String Configuration





# Subsystem Characteristics

Resource	System		Current Best Estimate	Basis
Mass (kg)	Thruster		12.7	PM Actual, w/o harness
	PPU		33.9	EM Actual
	PMS	HPA	1.9	EM Actual, w/plate & Test Support Equip.
		LPA	3.1	EM Actual, w/plate & Test Support Equip.
	Gimbal		6	Breadboard Actual
Envelope (cm)	Thruster		55 dia. x 44 length	PM Actual
	PPU		42 x 53 x 14	EM Actual
	PMS	HPA	33 x 15 x 6.4	EM Actual
		LPA	38 x 30.5 x 6.4	EM Actual
	Gimbal		72 cm corner-corner, 61 cm flat-flat	Breadboard Actual
Power (W)	Thruster <sup>[1]</sup>		540-6860	PM Actual
	PPU		610-7220	Breadboard Actual
	PMS	HPA	4.3	EM Actual
		LPA	15.9	EM Actual
	Gimbal		N/A	-

<sup>[1]</sup> Input power to the thruster from the PPU.



# Transition to Flight



# Lessons Learned/Independent Review

- Project activities are being conducted to increase the likelihood of transitioning the NEXT IPS technology to flight in the near-term:
  - Reviewing Dawn IPS ‘lessons-learned’ and implementing strategies to mitigate the likelihood of experiencing similar difficulties;
  - Conducting independent reviews of NEXT technology status with representation from the user community and incorporating the feedback into the development plan;
  - Identifying additional technology development and validation activities which may be of value in transitioning the TRL6 IPS technology to flight and reduce barriers to 1st-user implementation (reduce non-recurring costs, etc.).
- The NEXT project has placed particular emphasis on key aspects of IPS development with the intention of avoiding the difficulties experienced by the Dawn mission in transitioning the NSTAR-based technology to an operational ion propulsion system



# Lessons Learned

- Detailed review of Dawn (provided by IPS manager) and NSTAR lessons-learned conducted
- NEXT systematically attacking issues identified under these programs – example
  - Documentation
    - Dawn – inadequate Thruster and PPU documentation
    - NEXT – EM PPU manufactured by flight production group with all documentation (manufacturing drawings and assembly instructions) now under configuration control;
    - NEXT PM thruster design and assembly documentation has been updated with PM1R changes and placed under design control for future build cycles



# Lessons Learned

- Additional examples
  - Propellant Management
    - Dawn – Complex, bulky, and required extensive modification to satisfy requirements
    - NEXT – DS-1 and Dawn feed system engineers heavily involved in NEXT design from project initiation; PMS design incorporates lightweight, compact design
  - Thruster
    - Dawn – Complex design elements, difficult to manufacture and assemble; long duration test results impacted flight configuration
    - NEXT – Thruster designed for manufacturability and assembly; extensive testing to evaluate erosion mechanisms conducted on EM hardware – resulting in modifications implemented on both EM and PM hardware and presently under extensive evaluations prior to committing to qualification build



# Technology Readiness

- Programmed FY08 In-Space activities will bring NEXT to a high state of readiness for FY08/09 AO's
  - Complete functional and qual-level environmental testing of key system elements
  - Thruster Long Duration Test has exceeded throughput requirement of 300 kg
  - System Integration Test with most mature hardware products
- NEXT is approaching TRL 6 in CY 2008
  - Key proposal requirement in AO guidance





# Transition to Flight Strategy

- Successfully complete all planned technology development activities for NEXT
- Reduce as much first user risk as future resources will allow. Work with users to jointly identify, address, and mitigate risks.
- Involve mission centers in upcoming system integration testing and the Project Validation Review
- Establish in-place NEXT ion thruster hardware at Aerospace Corp. in CY08 for independent technology assessments
- Continue interactions with mission stakeholders to support mission studies using the NEXT IPS



# Summary

- NEXT project activities through 2007 have brought next-generation ion propulsion technology to a sufficient maturity level
- In-Space Propulsion Technology tasks will complete the majority of the NEXT technology validation in FY08